



Plasticity

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Version 22-07-14



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Topics



Multiplication of Dislocations

- Nucleation
- Glide Sources (Single-Arm, Two-Arm)
- Cross-Slip Sources
- Climb Sources
- Helical Source
- Other Sources of Dislocations



Nucleation



- In Ch. 3d, we have seen that vacancies spontaneously form at finite temperature due to rather low formation enthalpy and gain in entropy by a configurational contribution.
- In Ch. 4c, we have seen that the formation enthalpy of dislocation lines is orders of magnitude larger. Hence, there is nothing like an equilibrium density.

At 0 K (no thermal fluctuations), the critical stress to form a dislocation loop is in the order of $\tau_c \approx \frac{G}{10}$ at a critical size of the loop of 3b (same meaning of critical as in typical nucleation theory for other subjects). If smaller stresses in the order of ordinary yield strength of metals are considered, the critical sizes are in the order of several hundred b. Even increasing temperatures, cannot sufficiently support the nucleation of loops.





- In Ch. 4c, we have seen that a glissile dislocation segment can rotate about a sessile segment.
- By every revolution, the slip step on the surface of the crystal increases by one Burgers vector.
- The glissile segment tends to form a spiral due to the relaxed structure of the dislocation at the surface/discontinuity of the crystal. The length of the dislocation line increases:



Single-arm glide source: initial state and after several revolutions





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Slipped regions of the same.





In case of a formation of the single arm by dislocation intersection (jog), the stress for passing has to be considered. As seen in Ch. 4d, the stress for passing by significantly increases for closely spaced dislocations. Hence, many intersection processes have to produce sufficiently large jogs:









Dislocation multiplication TiAl (Ti-48Al-2Cr) after compression testing at 300 K to 3 % strain.

F. Appel et al.: "Recent Progress in the Development of Gamma Titanium Aluminide Alloys" in Adv. Eng. Mat. 2 (2000) 699-720





Glide component of the interaction force between two anti-parallel edge dislocations (Ch. 4d):

$$\frac{F_x}{L} = -\frac{G b^2}{2\pi (1 - \nu)} \frac{x \cdot (x^2 - y^2)}{(x^2 + y^2)^2}$$

Maximum force:

F_{χ}^{\max}	$G b^2$	1
L	$-\frac{1}{8\pi (1-v)}$	\overline{l}

Glide component of the interaction force between two anti-parallel screw dislocations (Ch. 4d):

$$\frac{F_x}{L} = -\frac{G \ b^2}{2\pi} \frac{x}{x^2 + y^2}$$

Maximum force:

$$\frac{F_x^{\max}}{L} = \frac{G \ b^2}{4\pi} \frac{1}{l}$$





The critical stress for the activation of the source is: τ_c b = F_x^{max}/L.
Hence, for the single-arm source τ_c = (G b/(8π (1-ν)) ... G b/(4π)) 1/l follows.
For reasonable yield strengths of roughly τ ≈ G/(1000) ... G/(100), the jog must be of l ≈ 6 ... 60 b or 8 ... 80 b in length for edge or screw dislocations, respectively.

The lower bound is realistic for jog-forming intersections.





- By assuming another pinning point, the single-arm source converts into a two-arm source, well-known as the Frank-Read source.
- Due to the rotation about the pinning points, the initially straight dislocation line transforms into an arc.
- The back stress by the arcs increases until the semi-circle configuration is achieved with $\tau_c = \frac{G b}{l}$ at $R = \frac{l}{2}$. Every other configuration needs lower stress to be achieved.
- By spiraling around, anti-parallel dislocation segments meet and annihilate. A new dislocation loop around the original dislocation segment is formed. The process continues in the same way.
- Due to the large size of the loops, the loops expand under the applied stress.
- Any pile-up of the dislocation loops results in back stress and potential de-activation of the source.







Two-arm source: various states.







Two-arm source: various states with tangent circles to visualize curvature.







Slipped regions of the same: (upper part) Z shape, (lower part) U shape.







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- Assuming again stresses in the order of $\tau \approx \frac{G}{1000} \dots \frac{G}{100}$, the segment enclosed by the pinning points must be of $l \approx 10^3 \dots 10^2 b$ in length.
- For the Z shape, the segment could be a result of intersection processes. It would be a jog. Since every intersection process only leads to an increase of 1b, a total length of 10³ ... 10² b is only reasonable when another source on the same slip plane is already operating.
- The U shape might originate from cross-slip processes when the points of slip plane change are effectiently pinned (for example by dissociation). This process is conceivable.







Two-arm source by cross-slip.



Significance in Experimental Results



- The increase of the width of deformation bands during plastic deformation indicates the significance of cross-slip in dislocation multiplication.
- The deformation bands gradually increase their thickness during plastic deformation by cross-slip.



Development of a single dislocation segment (large etch pits) to a deformation band (multiple small etch pits) by cross-slip and dislocation multiplication in LiF.

D. Hull, D. J. Bacon: "Introduction to Dislocations", Amsterdam, etc.: Elsevier (2011)



Significance in Experimental Results



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Development of deformation band thickness in LiF.

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Loop Formation by Cross Slip



- In materials with high Peierls barriers and preferred screw character of dislocations (A2 metals and intermetallics), segmentwise cross-slip can lead to the formation of prismatic loops (see Ch. 3a, only edge character along the dislocation loop).
- It is also observed in particle strengthened materials, since the induced cross-slip by the obstacle can lead to this configuration (one kind of bypassing the particle, Orowan mechanism).







Loop Formation by Cross Slip



D. Caillard , M. Legros & A. Couret: "Extrinsic obstacles and loop formation in deformed metals and alloys" in Phil. Mag. 93 (2013) 203-221 F. Appel et al.: "Recent Progress in the Development of Gamma Titanium Aluminide Alloys" in Adv. Eng. Mat. 2 (2000) 699-720



Loop Formation by Cross Slip





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- For the activation of climb sources, a supersaturation in vacancies is necessary. This can be achieved for example by quenching from higher temperatures or irradiation.
- Similar to what is observed for the Frank-Read source, the critical point is the semi-circle configuration $R = \frac{l}{2}$. The amount of supersaturation can, therefore, be estimated by $\ln(\frac{x}{x_0}) = \frac{G \ b \ \Omega}{l \ k_B \ T}$ (see Ch. 3c for the chemical force on dislocation lines).
- Since we assume a climb process, the Z shape is not formed from a jog but from a kink.









Hence, $\Omega \approx b^3$ at T = 300 K and with $G \approx 25$ GPa as well as $b \approx 2.9$ Å lead to (AI):

$$l \approx \frac{150}{\ln\left(\frac{x}{x_0}\right)} b$$

- A supersaturation of only $\ln\left(\frac{x}{x_0}\right) = 25$ leads to a small kink of only $l \approx 6 b$.
- Compare this with following quenching process

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$$x_0 = e^{\frac{\Delta S_V^2}{k_B}} e^{-\frac{\Delta H_V^2}{k_B T}}$$
 with $\Delta S_V^P = 2.4 k_B$, $\Delta H_V^F = 1.27$ eV (again Al)

- yields $x_0 = 5 \cdot 10^{-21}$ and $x = 2 \cdot 10^{-10}$ at T = 300 and 600 K, respectively
- the supersaturation for quenching from 600 to 300 K is then

$$\ln\left(\frac{x}{x_0}\right) \approx 25$$





Due to the small excess vacancy concentration for activation of the climb source, climb sources are frequently found.

Bardeen-Herring source

growth of prismatic loops

B-H source and growth of prismatic loops by vacancy agglomeration in TiAl at 820 K.

F. Appel et al.: "Recent Progress in the Development of Gamma Titanium Aluminide Alloys" in Adv. Eng. Mat. 2 (2000) 699-720







Bardeen-Herring source ~

many small prismatic loops

The vacancy agglomeration of the small loops retards the expansion of large loops. At the bulge, less small loops are formed due to cross-slip and, hence, the larger loops can expand further. Note that not all loops are visible for this diffraction condition!

Prismatic loops in an AI-4Cu single crystal subsequent to 793 K/2 h/quenching and ageing at 266 K with compression load along [011] at 30 MPa. Viewing direction is along [110].

A. Sato , Y. Sugisaki & T. Mori: "Observation of dislocation sources in a quenched and stress-aged Al-4 wt% Cu alloy single crystal" in Phil. Mag. 51 (1985) 133-143







Prismatic loops in AI-3.5Mg subsequent to quenching from 550 °C.

D. Hull, D. J. Bacon: "Introduction to Dislocations", Amsterdam, etc.: Elsevier (2011)



Karlsruhe Institute of Technology





↑*b*

Helical source: various states.



Helical Source





F. Appel et al.: "Recent Progress in the Development of Gamma Titanium Aluminide Alloys" in Adv. Eng. Mat. 2 (2000) 699-720



Other Sources



- Heterogonous nucleation at interfaces is also an important contribution to dislocation multiplication.
- Following issues during assessment have to be considered:
 - Interfaces are usually points of stress concentrations. Hence, stresses might be significantly higher than expected from external load.
 - High interface density leads to high nucleation rates. In contrast very narrow interface spacing can restrict the free motion of the arms of dislocation sources and block the dislocation multiplication.



Summary



- Dislocation do not form spontaneously.
- Dislocations nucleate at surfaces and interfaces in heterogonous materials.
- Dislocations sources can be grouped by the major contribution to dislocation motion: glide, cross-slip and climb. In general, singlearm and two-arm sources are possible.

